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PALM INTRANET**Inventor Information for 10/764650**

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US 20060036162 A1	US- PGPUB	20060216	Method and apparatus for guiding a medical instrument to a subsurface target site in a patient	600/424		Shahidi; Ramin et al.
US 20050085718 A1	US- PGPUB	20050421	Systems and methods for intraoperative targetting	600/424	128/922; 600/109; 600/117; 600/443	Shahidi, Ramin
US 20050085717 A1	US- PGPUB	20050421	Systems and methods for intraoperative targetting	600/424	128/922; 600/109; 600/117; 600/443	Shahidi, Ramin
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US 20020077544 A1	US- PGPUB	20020620	Endoscopic targeting method and system	600/424	606/130	Shahidi, Ramin
US 20020077543 A1	US- PGPUB	20020620	Method and apparatus for tracking a medical instrument based on image registration	600/424	606/130	Grzeszczuk, Robert et al.
US 20020075994 A1	US- PGPUB	20020620	Virtual fluoroscopic system and method	378/62		Shahidi, Ramin et al.
US 20020010384 A1	US- PGPUB	20020124	Apparatus and method for calibrating an endoscope	600/118	600/117	Shahidi, Ramin et al.
US 20010037064 A1	US- PGPUB	20011101	Method and apparatuses for maintaining a trajectory in sterotaxi for tracking a target inside a body	600/429	606/130	Shahidi, Ramin
US 20010029333 A1	US- PGPUB	20011011	Method and apparatus for volumetric image navigation	600/429	600/425; 600/427	Shahidi, Ramin
US 20010025183 A1	US- PGPUB	20010927	Methods and apparatuses for maintaining a trajectory in sterotaxi for tracking a target inside a body	606/130		Shahidi, Ramin
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US 6674833 B2	USPAT	20040106	Virtual fluoroscopic system and method	378/4	378/62; 378/94	Shahidi; Ramin et al.
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